

ALICE ITS: Operational Experience, Performance and Lessons Learned

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ALICE (A Large Ion Collider Experiment) is a general purpose heavy-ion experiment designed for the study of strongly-interacting matter at the extreme energy densities reached in Pb–Pb collisions at the CERN LHC, where the deconfined phase of hadronic matter known as Quark–Gluon Plasma (QGP), is formed.

The innermost detector of ALICE is the Inner Tracking System. In its first release, it consists of six cylindrical layers of silicon detectors based on different technologies: two inner layers of pixel sensors (Silicon Pixel Detector), two intermediate layers of drift sensors (Silicon Drift Detector), two outer layers of strip sensors (Silicon Strip Detector). The ITS is used for the reconstruction of primary and secondary vertices, for particle tracking, for a precise determination of the impact parameter and for particle identification at low momentum.

In this report, after a brief description of the three subdetectors, the operational experience with the first ITS implementation is summarized, the status and the performance of the detector are described and the lessons learned are discussed after the end of its operation coinciding with the completion of the LHC Run2.

The 28th International Workshop on Vertex Detectors - Vertex2019

13-18 October, 2019

Lopud, Croatia

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1. Introduction

ALICE (A Large Ion Collider Experiment) [1] is designed to study the strongly-interacting matter and in particular the properties of the Quark–Gluon Plasma, a deconfined phase of matter produced in extreme energy-density conditions, such as in ultra-relativistic heavy-ion collisions. Besides Pb–Pb collisions, the ALICE experimental program includes also pp and p–Pb collisions, which are needed as reference for the study of the underlying collision dynamics. The experimental apparatus can be divided into two different pseudorapidity regions. The forward muon arm covers the forward pseudorapidity region $-4.0 < \eta < -2.5$ and is used to measure heavy-flavoured hadrons, quarkonia and light vector mesons. The central barrel covers the pseudorapidity region $|\eta| < 0.9$ and the full azimuthal angle. The detectors in the central barrel are embedded in a solenoidal magnet, which provides a magnetic field up to 0.5 T. The two main tracking detectors in the central barrel are the Inner Tracking System (ITS) [2] and the Time Projection Chamber (TPC) [3]. The low material budget of ITS and TPC ($\sim 10\% X_0$) allows the reconstruction of charged-particle trajectories in a wide transverse momentum range (0.1–100 GeV/c). Moreover, the central-barrel detectors allow the particle identification (PID) up to 20 GeV/c through the measurement of the specific energy loss dE/dx in the ITS and in the TPC and of the time of flight in the dedicated detector (TOF [4], resolution of ~ 60 ps in Pb–Pb collisions).

THE ALICE DETECTOR

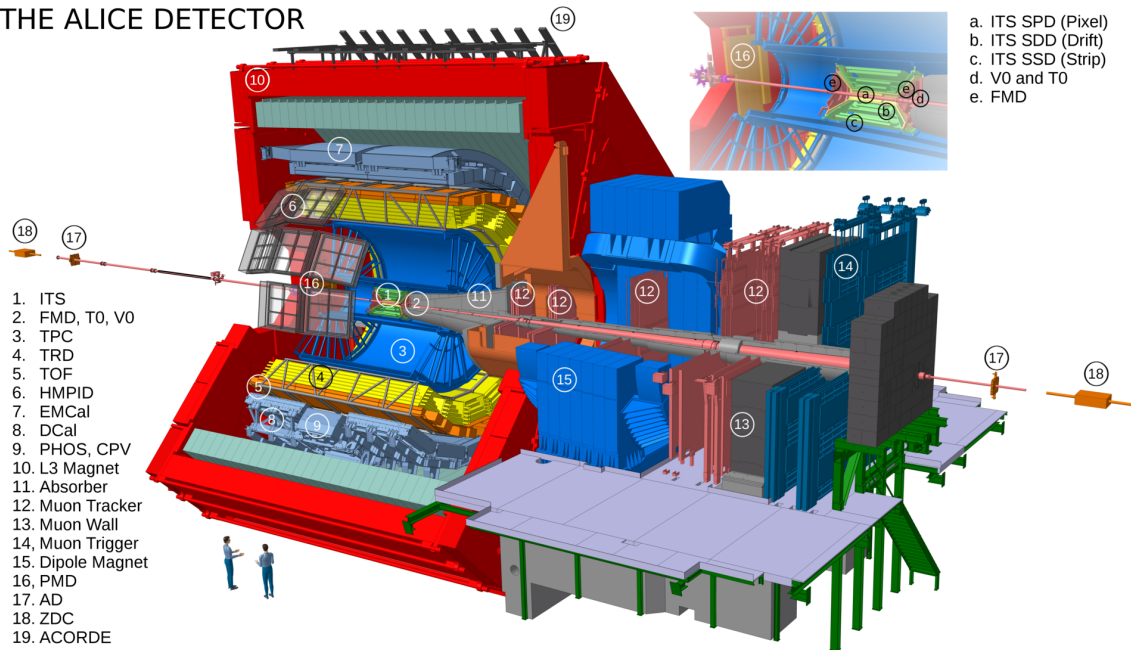


Figure 1: Schematic of the ALICE apparatus. A zoom of the ITS is shown on the top-right corner.

2. The Inner Tracking System (ITS)

The ITS is the detector closest to the interaction point and has several purposes. It is used for the reconstruction of the collision point (primary vertex), with a resolution of $10 \mu\text{m}$ in central

22 Pb–Pb collisions, and the displaced vertices (secondary vertices), with a resolution better than 100
 23 μm . The precision of the primary vertex reconstruction, together with the possibility of measuring
 24 the impact parameter, i.e. the distance of closest approach of a track to the vertex, with a resolution
 25 of $\sim 60 \mu\text{m}$ at $p_T = 1 \text{ GeV}/c$, makes it possible to study particles characterised by a short decay
 26 length, such as open heavy-flavoured hadrons. The ITS allows the reconstruction of the trajectories
 27 down to $0.1 \text{ GeV}/c$. Finally, the ITS can be used for PID at low transverse momentum. The ITS
 28 consists of six cylindrical layers of silicon detectors based on different technologies. A representa-
 29 tion of the ITS within the ALICE experimental apparatus is shown in Fig. 1 and the characteristics
 30 of the ITS and its subdetectors are listed in Table 1.

31

Layer	Detector	Radius (cm)	Length (cm)	Channels	Area (m^2)	Res. (μm)		M.B. (% X_0)
						$r\phi$	z	
1	SPD	3.9	28.2	3.3 M	0.07	12	100	1.14
2		7.6	28.2	6.5 M	0.14			1.14
3	SDD	15.0	44.4	43 k	0.42	35	25	1.13
4		23.9	59.4	90 k	0.89			1.26
5	SSD	38.0	86.2	1.1 M	2.20	20	830	0.83
6		43.0	97.8	1.5 M	2.80			0.83

Table 1: Characteristics of the ITS, layer by layer. *Res.* is the resolution, along the bending direction ($r\phi$) and the beam axis (z). *M.B.* is the material budget, expressed in terms of radiation lengths (X_0).

32 2.1 The Silicon Pixel Detector (SPD)

33 The two innermost layers constitute the Silicon Pixel Detector (SPD), based on hybrid pixel
 34 detectors with binary output. The SPD consists of 120 Half-Stave modules, grouped in two Half-
 35 Barrels divided in the z direction. Each Half-Barrel contains 10 Half-Sectors, each constructed from
 36 six Half-Staves, two from the first and four from the second layer. The Half-Stave is composed of
 37 two ladders, each containing one two-dimensional $200 \mu\text{m}$ thick silicon sensor matrix and five
 38 $150 \mu\text{m}$ thick bump-bonded readout chips each. The matrix has 256×160 reversely biased (50 V)
 39 p^+n diodes, forming cells $50 \mu\text{m}$ wide ($r\phi$) and $425 \mu\text{m}$ long (z). The binary output is readout at
 40 10 MHz . The detector is equipped with a C_4F_{10} evaporative cooling system.

41 The SPD is the only ITS subdetector which contributes to the ALICE trigger (L0). Each pixel
 42 readout chip outputs the data of the fired pixels and one Fast-OR signal set to 1 if at least one of
 43 the 8192 related pixels is fired. The Fast-OR signals are produced at 10 MHz and are used by the
 44 ALICE Central Trigger Processor to produce High Multiplicity L0 trigger, based on the number
 45 of SPD tracklets (segments obtained coupling pairs of points on the two layers), and Double-Gap
 46 Diffractive trigger, in which two cones are looked for in mid-rapidity region and selections are
 47 applied to the opening angle as well as to the number of tracklets.

48 **2.2 The Silicon Drift Detector (SDD)**

49 The Silicon Drift Detector (SDD) equips the two intermediate layers of the ITS. It consists of
50 260 drift modules, each composed of a 300 μm thick drift sensor and two custom hybrid readout
51 boards. The sensitive area of the module is divided into two drift regions along the bending direc-
52 tion ($r\phi$) by the central cathode at -1.8 kV. In each drift region and on both detector surfaces, 291
53 p^+ cathode strips (120 μm pitch) fully deplete the detector and generate a uniform electric drift
54 field (~ 500 V/cm), parallel to the module surface, towards 256 collection anodes (294 μm pitch)
55 aligned to the beam axis.

56 The drift speed is about 6.7 $\mu\text{m/s}$ and is monitored by means of MOS charge injectors: in each
57 drift region there are three lines of 22 MOS injectors, close to the anodes, in the middle of the drift
58 region and close to the central cathode. The drift speed is measured in specific calibration runs at
59 the beginning of each LHC fill. The analog SDD information is digitalized by 10-bit ADCs at 20
60 MHz at the level of the front-end electronics developed on CMOS 0.25 μm . The SDD is provided
61 with a leak-less water cooling system.

62 **2.3 The Silicon Strip Detector (SSD)**

63 The two outermost layers of the ITS constitute the Silicon Strip Detector (SSD). It consists
64 of 1698 modules, each composed of 768 double-sided strip sensors, with a thickness of 300 μm ,
65 connected with two HAL25 front-end chips. The analog signals are extracted from the detector and
66 digitalized by 12-bit ADCs directly in the readout electronics placed outside the ALICE solenoid
67 magnet.

68 The strips on the P-side and on the N-side of the sensor have a pitch of 95 μm , a length of 40
69 mm and angles of, respectively, 7.5 mrad and 27.5 mrad with respect to the beam axis, to define a
70 stereo angle of 35 mrad, which is a compromise between stereo view and reduction of ambiguities
71 due to high particle density, to ensure the best position resolution in the bending direction. The p^+n
72 reverse bias is optimized in the range 20–80 V. The SSD is provided with a leak-less water cooling
73 system shared with the SDD and, due to the sensitivity of the detector to the air humidity, an air
74 dryer system is also used to keep the absolute humidity between 1 and 1.5 g/kg.

75 **3. The ITS operational performance**

76 The ITS operational efficiency is summarized in Table 2, which reports the availability of
77 the ITS subdetectors, expressed as the fraction of the total ALICE data-acquisition time each sub-
78 detector participated in, and the acceptance, indicated as the fraction of modules in acquisition.
79 Generally, for all the detectors the availability was stable during Run2 and improved with respect
80 to Run1. The improvement was possible thanks to the firmware update of the readout electronics,
81 to the automation of recovery procedures and to the interventions that took place during Run1 and
82 the following Long Shutdown (LS1).

83 In this regard, it is useful to remember that in 2011 only 63% of the SPD could be powered on,
84 due to an insufficient flow of the liquid freon in the cooling system, with filters clogged by metal
85 and graphite fragments. Clogged filters have been drilled in 2012–2013, restoring the number of
86 active modules to 92% at the end of Run1. During Run2, the SPD acceptance and availability were

	Availability (%)			Acceptance (%)		
	SPD	SDD	SSD	SPD	SDD	SSD
Run1 (2013)	96.0	92.0	96	92	87	91
Run2 (2015–2016)	99.6	98.4	98.6	93	83	91
Run2 (2017)	99.9	99.5	100.0	93	82	91
Run2 (pp 2018)	99.6	99.8	99.8	92	81	91
Run2 (Pb–Pb 2018)	98.8	95.7	99.6	92	81	91

Table 2: Availability and acceptance of the three ITS subdetectors during the last part of Run1 and Run2, indicated as fraction of data acquisition-time and of number of active modules, respectively. In the 2018 Pb–Pb data taking SDD show a reduced availability due to SDD exclusion from rare triggers.

87 very stable: no radiation effect appeared as increase in noisy channels and temperature thanks to
 88 the reduced luminosity leveled to $2.6 \text{ Hz}/\mu\text{barn}$ in the ALICE interaction point that produced a low
 89 total ionizing dose (TID) at the SPD position (17.4 krad). Still, a continuous slowly increasing
 90 trend of the bulk current was observed for some Half Staves of the innermost layer, and was fixed
 by a careful tuning of current limits before each data taking. Additionally, another effect was

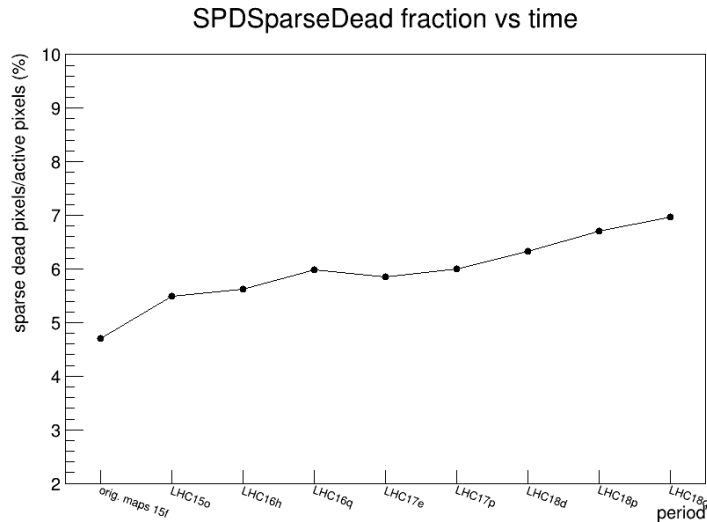


Figure 2: SPD sparse dead pixel fraction trend in LHC Run2 beam periods from 2015 to 2018.

91 observed starting from the 2015 data taking: a continuous slight increase of the fraction of sparse
 92 dead pixels (from $\sim 4.6\%$ in 2015 to $\sim 7\%$ in 2018, see Fig. 2). The dead pixels are mainly located
 93 at the edges of the bump-bonded readout chips: this is consistent with a bump-bonding detachment
 94 process probably induced by mechanical and thermal stress. This kind of issue is overcome in the
 95 new release of the ITS that is based on monolithic active pixel sensors (MAPS) [5]. Globally, no
 96 effect on the performance in terms of detection efficiency and space accuracy has been observed in
 97 Run2 for SPD.
 98

99 Concerning the SDD, the most recurring problems during Run1 were the loss of commu-
 100 nication of one module and the presence of an error in the Common Data Header (CDH), interpreted as
 101 a consequence of a Single Event Upset (SEU). The recovery time to reset the configuration of the
 102 front-end electronics was reduced to 800 μ s in the transition between Run1 and Run2, by upgrad-
 103 ing the readout boards with more performing FPGA; thanks to these new boards, a new firmware
 104 was also designed, with an automatic procedure to detect event by event noisy chips and eventually
 105 to reload the configuration parameters without stopping the data acquisition. This improved the
 106 availability of the detector and reduced the global acquisition dead time. On the other hand, since
 107 the beginning the fraction of active modules was lower with respect to the other subdetectors, as
 108 indicated in Table 2, because of communication loss with some modules during installation and
 109 Run1. Also, during an LHC beam dump close to ALICE, the inner SDD layer suffered from high
 110 radiation exposure causing the loss of many MOS injectors. During all Run2 SDD behaved well,
 111 featuring stable fraction of active modules, stable and low noise level (~ 350 equivalent electrons),
 very stable baseline and gain.

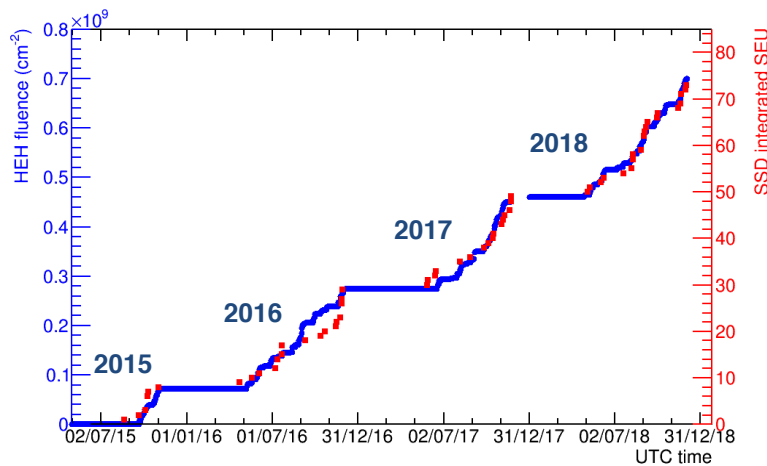


Figure 3: Integrated number of SEU events and integrated HEH fluence in Run2 (2015–2018).

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114 One of the most recurrent problems with the SSD in Run1 and Run2 was the occurrence of
 115 SEU events affecting the SRAM FPGA of the Front End Read Out Modules (FEROM). FEROM
 116 modules are located in the cavern, close to the solenoid magnet, in a region where the TID at the
 117 end of Run2 was ~ 0.34 krad and SEUs were not expected. In Fig. 3 the integrated number of
 118 SEUs since 2015 is shown, together with the integrated fluence of High Energy Hadrons (HEH),
 119 measured with a sensor within the FEROM crate. The correlation between the number of SEU
 120 events and the integrated fluence is evident and indicates that the origin of these events is actually
 121 due to the beam presence and not to electronics ageing effects. After Run1 some countermeasures
 122 were implemented. In particular, the PROMs in the FEROMs were replaced with new radiation
 123 tolerant PROMs and the FPGA firmware was updated, reducing the recovery time from 20 minutes
 124 to 5 minutes in Run2. At the beginning of Run2, SSD suffered also from air humidity leading to
 125 an increase of leakage currents: interventions on the ventilation machine in 2015 and the addition
 126 of an air dryer system in 2016 allowed to fix these issues. In the 2018 Pb–Pb data taking SSD was
 the most stable of the ITS detectors.

127 4. The ITS detector and physics performance

128 The ITS plays a crucial role in the reconstruction of the primary and secondary vertices. The
 129 algorithm used to perform this task is based on an iterative procedure using tracks reconstructed
 130 in the whole ALICE central barrel with the ITS and the TPC. To extend the transverse momentum
 131 acceptance down to $0.1 \text{ GeV}/c$ and to recover tracks not reconstructed in TPC, an ITS-standalone
 132 tracking algorithm has been developed. The efficiency for tracks with at least 2 points in ITS is
 133 $\geq 95\%$ and is constant in the transverse momentum range; Fig. 4 (left) shows the efficiency for
 134 tracks with (at least) one hit in SPD and a hit in TOF for 2016 p–Pb collisions at $\sqrt{s_{NN}} = 5.02 \text{ TeV}$.

135 As anticipated, the ITS contributes to the ALICE particle identification measuring the ionizing
 136 energy loss dE/dx in the four outermost layers via the readout of the analog signal proportional to
 137 the charge released in the detector layers [6]. Fig. 4 (right) shows an example of the mean energy
 138 deposition as a function of the momentum measured in Pb–Pb collisions at $\sqrt{s_{NN}} = 5.02 \text{ TeV}$. The
 139 ITS particle identification combined with the standalone tracking allows for a $K - \pi$ and a $K - p$
 140 separation in the range $(0.1\text{--}0.45) \text{ GeV}/c$ and $(0.1\text{--}1) \text{ GeV}/c$ respectively.

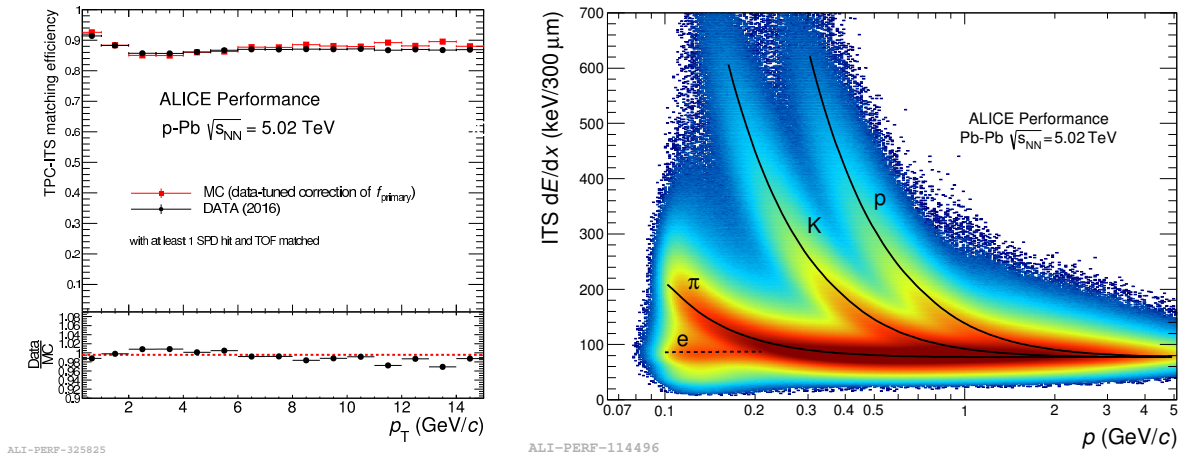


Figure 4: Run2 ITS detector performance. Left: TPC-ITS matching efficiency vs momentum for tracks with at least 1 hit in SPD and a hit in TOF in p–Pb collisions at $\sqrt{s_{NN}} = 5.02 \text{ TeV}$. Right: ITS specific energy loss of electrons, pions, kaons and protons vs momentum in Pb–Pb collisions at $\sqrt{s_{NN}} = 5.02 \text{ TeV}$.

141 The resolution of the track impact parameter d_0 , calculated as the distance of closest approach
 142 of a given track to the vertex, allows to define the tracking precision of the system. In Fig. 5 (left)
 143 the impact parameter resolution in the $x - y$ plane, for identified ITS-TPC tracks, is reported as
 144 a function of the transverse momentum for three different collision systems [6]. For all of them
 145 the d_0 resolution is about $60 \mu\text{m}$ at $1 \text{ GeV}/c$; the contribution of the primary vertex resolution
 146 is not subtracted. The precise measurement of the track impact parameter and the capability to
 147 separate the primary and secondary vertex allows the inclusive reconstruction of rare particles via
 148 their hadronic decays: Fig. 5 (right) shows the invariant mass spectrum of the short-lived ($c\tau \sim$
 149 $123 \mu\text{m}$) D^0 meson decaying to $K\pi$ pairs.

150 5. Lessons learned and Conclusions

151 The ALICE Inner Tracking System has been successfully in operation during LHC Run1 and

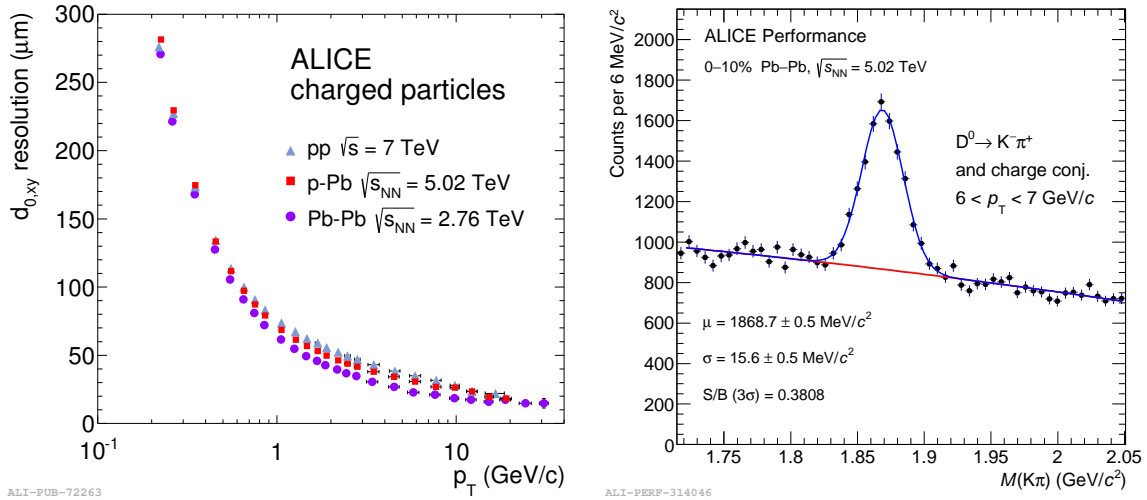


Figure 5: Run2 ITS physics performance. Left: impact parameter resolution in the $x - y$ plane as a function of the transverse momentum in pp collisions at $\sqrt{s} = 7$ TeV, p-Pb collisions at $\sqrt{s_{NN}} = 5.02$ TeV and in Pb-Pb collisions at $\sqrt{s_{NN}} = 2.76$ TeV. Right: $K\pi$ invariant mass in D^0 mass region for central Pb-Pb collisions at $\sqrt{s_{NN}} = 5.02$ TeV.

152 Run2, with high efficiency and stable participation in pp, p-Pb and Pb-Pb data takings. During
 153 Run2, procedures have been implemented to minimize the recovery time related to SEU events
 154 and to issues arising when reloading the configuration parameters of the readout electronics. SPD
 155 fully contributed to the L0 trigger algorithms. SPD, SDD and SSD performed remarkably well
 156 and according to the specifications, the physics performance was in agreement with the design
 157 requirements and was stable in time.

158 At the end of operation of the first release of the ITS some lessons learned can be discussed.
 159 As a global consideration, the three subdetectors, based on different technologies, actually worked
 160 as three independent detectors with different features, needs and peculiarities, so that no standard-
 161 ization was possible in procedures related to front-end electronics configuration, data acquisition,
 162 detector calibration. Indeed, each subdetector had its own Detector Control System (DCS) to re-
 163 motely control the underground hardware, to apply specific operation strategies (e.g. SEU recovery
 164 and security operations during beam injections), to monitor operational conditions and data quality
 165 for spotting misconfigurations during data taking (Data Quality Monitor, DQM). In the same way,
 166 each subdetector had its own Experiment Control System (ECS) to perform specific operations like
 167 stand alone runs and calibrations; also the offline Quality Assurance procedure (QA) was different.

168 For SPD issues have appeared in the operation of the cooling system that, in future imple-
 169 mentations, could be eliminated by an even more attentive choice of the position of the filters on
 170 the feeding lines. A second point to be taken into account are the residual effects of mechanical
 171 and thermal stress actions developed during the detector running on the sensors bump bonded to
 172 the readout chips, which produced an (almost negligible) increase of the dead pixels number at the
 173 chip edges. Both aspects have been fully overcome in the Upgrade release of the ITS [5], presently
 174 in post assembly test phase: it is composed of seven layers of MAPS (no bump bonding!) and the
 175 upgraded Inner Barrel features a power absorption about 1/10 than the SPD one.

176 For SDD the main lesson learned is related to the drift speed calibration. It must be underlined
177 that ALICE could operate successfully an SDD system exploiting at best the two dimensional
178 capabilities provided by this technology thanks to several solutions implemented in the hardware
179 and in the readout and to a complex calibration scheme. The resolution along the anode rows
180 (see Table 1) was obtained by the well established collected charge centroid technique while the
181 resolution in the drift direction relied on the determination of the drift velocity that is sensitive to
182 temperature gradients in the SDD volume and to temperature variations with time. Calibration runs
183 were done at the beginning of each LHC fill, based on the signals of the three MOS injector lines
184 implanted at known distances from the collection anodes. The drift field, however, was intrinsically
185 not uniform enough to allow, this way, an evaluation of the hit position along the drift direction
186 at the precision level needed to fulfill the design requirements; to obtain the final resolution a
187 correction for the non-uniformity of the drift field was calibrated for each LHC fill based on the
188 precise information of the neighboring ITS layers.

189 For SSD the main lesson is related to humidity control of the air surrounding the detector, to
190 avoid increasing leakage currents that can lead to permanent damages. The second point, actually
191 the first one in terms of frequency, is related to SEUs occurrence, which can only be fixed either
192 by moving the frontend electronics farther from the beam line or by adding shielding material in
193 front of it. This was not viable in the past ALICE setup and has been attentively considered for the
194 Upgraded ITS.

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